# Global phase portraits of the quadratic systems having a singular and irreducible invariant curve of degree 3 

J. Llibre<br>Departament de Matemàtiques, Universitat Autònoma de Barcelona, Edifici C, 08193 Bellaterra, Barcelona, Catalonia, Spain<br>jllibre@mat.uab.cat<br>C. Pantazi<br>Departament de Matemàtiques, Universitat Politècnica de Catalunya, (EPSEB), Av. Doctor Marañón, 44-50, 08028 Barcelona, Spain<br>chara.pantazi@upc.edu


#### Abstract

Any singular irreducible cubic curve (or simply, cubic) after an affine transformation can be written as either $y^{2}=x^{3}$, or $y^{2}=x^{2}(x+1)$, or $y^{2}=x^{2}(x-1)$. We classify the phase portraits of all quadratic polynomial differential systems having the invariant cubic $y^{2}=x^{2}(x+1)$. We prove that there are 63 different topological phase portraits for such quadratic polynomial differential systems. We control all the bifurcations among these distinct topological phase portraits. These systems have no limit cycles. Only 3 phase portraits have a center, 19 of these phase portraits have one polycycle, 3 of these phase portraits have 2 polycycles. The maximum number of separartices that have these phase portraits is 26 and the minimum number is 9 , the maximum number of canonical regions of these phase portraits is 7 and the minimum is 3 .


Keywords: Poincaré disk, global phase portrait, singular curve, cubic curve, polycycles, canonical regions, separatrices.

## 1. Introduction and statement of the main result

Quadratic polynomial differential systems (or simply quadratic systems) are systems that can be written into the form

$$
\begin{equation*}
\dot{x}=P(x, y)=P_{0}+P_{1}+P_{2}, \quad \dot{y}=Q(x, y)=Q_{0}+Q_{1}+Q_{2}, \tag{1}
\end{equation*}
$$

where $P_{i}$ and $Q_{i}$ are real polynomials of degree $i$ in the variables $(x, y)$ and $P_{2}^{2}+Q_{2}^{2} \neq 0$.
An extensive literature is dedicated to the study of the quadratic systems these last years. For a good survey see the book of Reyn [Reyn, 1994] or the book of Artés et.al [Artés et al., 2021], and references therein. For example, the following families of quadratic systems have been studied: homogeneous [Coll et al., 1987], semi-homogeneous [Cairó \& Llibre, 1997], bounded [Dickson et al., 1970], reversible [Gavrilov \& Iliev, 2000; Coll et al., 2009], Hamiltonian [Artés \& Llibre, 1994a; Chow et al., 2002], Lienard [Dumortier \& Li, 1997], integrable using Carleman and Painlevé tools [Hua et al., 1996], rational integrable [Artés et al., 2007, 2010, 2009], the ones having a star nodal point [Berlinski, 1966], a center [Vulpe, 1983; Lunkevich \& Sibirskii, 1982; Coll et al., 2009; Vulpe, 1983], one focus and one antisaddle [Artés \& Llibre, 1994b], with a semi-elementary triple node [Artés et al., 2013], chordal [Gasull et al., 1986; Gasull \& Llibre, 1988], with

